

1 Notice

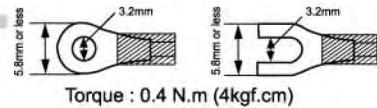
Please confirm the specification of controllers is tally with your request before using, and refer to this user manual in detail.

⚠ Danger

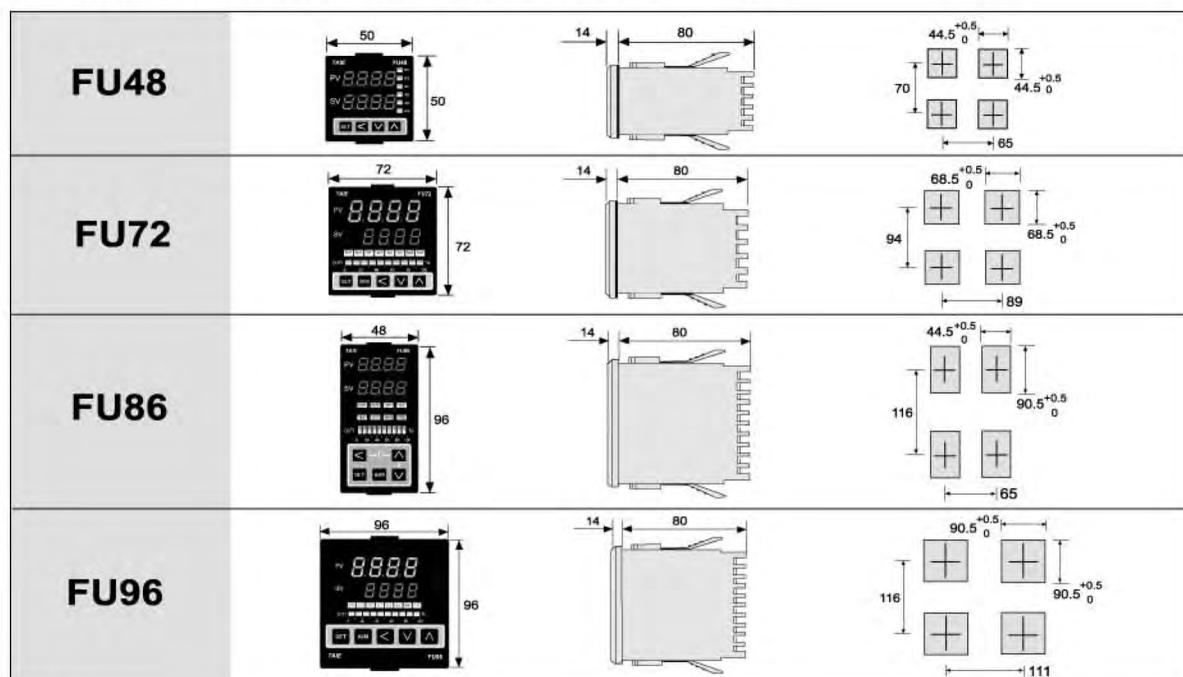
1. Danger ! Electric Shock !
 - Don't touch AC power wiring terminal when controllers power on to avoid electric shock !
 - Keep the power off when controllers wiring !

⚠ Warning

1. Please confirm the AC power wiring to controller is correct, otherwise it will be caused serious damage on controller.
(FU48 connecting with Pin 1 and 6, FU72/86/96 with Pin 1 and 2).
2. Be sure to use the rated power supply(AC85~265V or DC24V), otherwise it will be caused serious damage on controller.
3. Please confirm all wiring is connected with correct terminals (Input, Output and Alarm)
4. Use M3 screw-compatible crimp-on terminals with an insulation sleeve, as shown below
5. Avoid to install controller in the following sites:
 - I. A place where the ambient temperature may reach beyond the range from 0 to 50°C
 - II. A place where the ambient humidity may reach beyond the range from 50 to 85% RH.
 - III. A place where the controller likely contact with water, oil, chemicals, steam or vapor.
 - IV. A place where the controller is subject to interface with static electricity, magnetism and noise.
6. For thermocouple(TC) input, use shield compensating lead wire.
7. For RTD input, use shield wires with low resistance and the same materials among 3 wires.



2 External Dimension and Panel Cutout < Unit : mm >

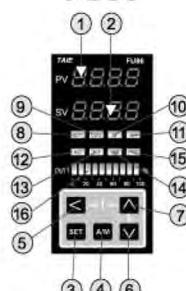


3 Parts Description

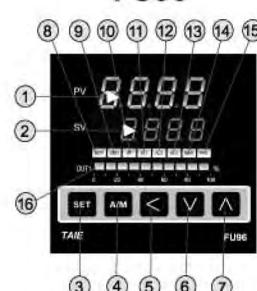
FU72



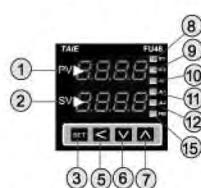
FU86



FU96



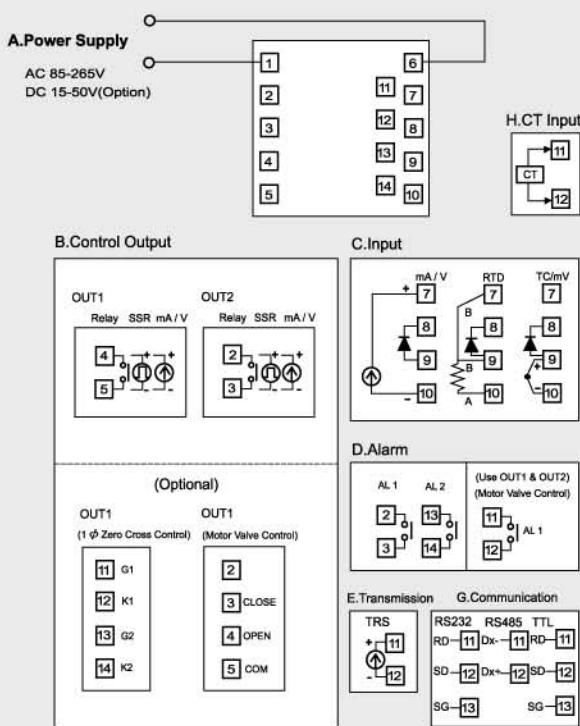
FU48



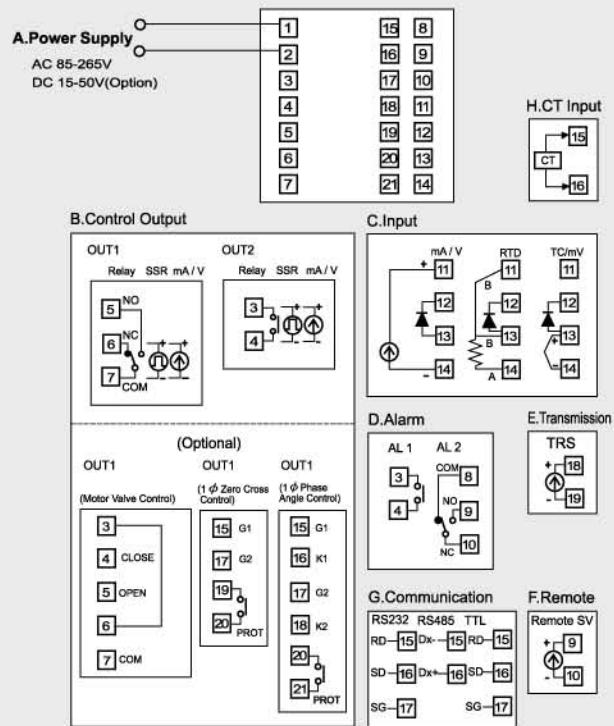
SYMBOL	NAME	FUNCTION	SYMBOL	NAME	FUNCTION
PV	① Measured value (PV)display	Displays PV or various parameter symbols(Red)	OUT1	⑧ OUT1 lamp	Lights when OUT 1 is on(Orange)
SV	② Setting value (SV)display	Displays SV or various parameter set values(Green)	OUT2	⑨ OUT2 lamp	Lights when OUT 2 is on(Orange)
SET	③ Set Key	Used for parameter calling up and set value registration	AT	⑩ Autotuning lamp	Lights when Autotuning is activated(Orange)
A/M	④ Auto/Manual key	Switches between Auto(PID) output mode and Manual output	AL1	⑪ Alarm 1 lamp	Lights when Alarm 1 is activated(Orange)
<	⑤ Shift Key	Shift digits when settings are changed	AL2	⑫ Alarm 2 lamp	Lights when Alarm 2 is activated(Orange)
V	⑥ Down Key (*Program Hold)	Decrease numbers (*Only for programmable controller)	AL3	⑬ Alarm 3 lamp	Lights when Alarm 3 is activated(Orange)
Λ	⑦ Up Key (*Program Run)	Increase numbers (*Only for programmable controller)	MAN	⑭ Manual output lamp	Lights when manual output is activated(Orange)
			PRO	⑮ *Program Running lamp	*Flashes when program running (Only for programmable controller)
			OUT1%	⑯ Output1% Bar-Graph display	Output 1% is displayed on 10-dot LEDs (Green)

4 Terminal Arrangement

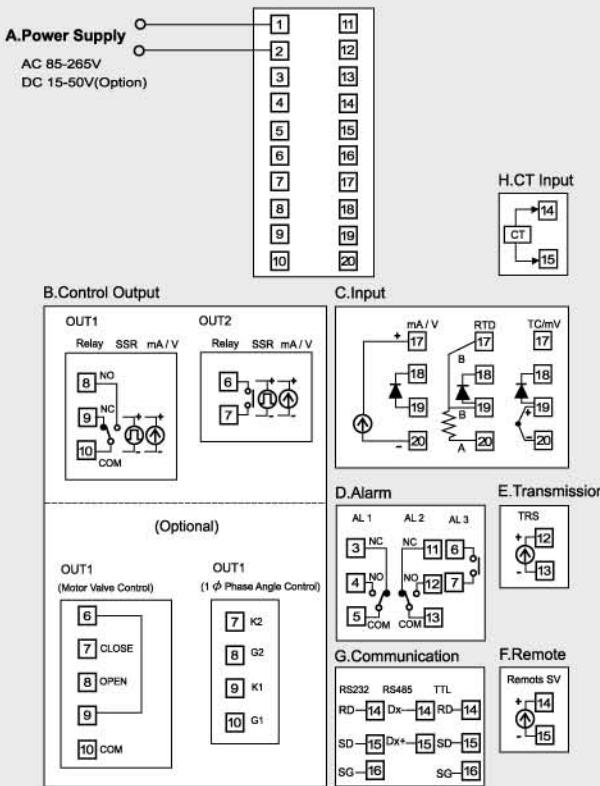
FU48



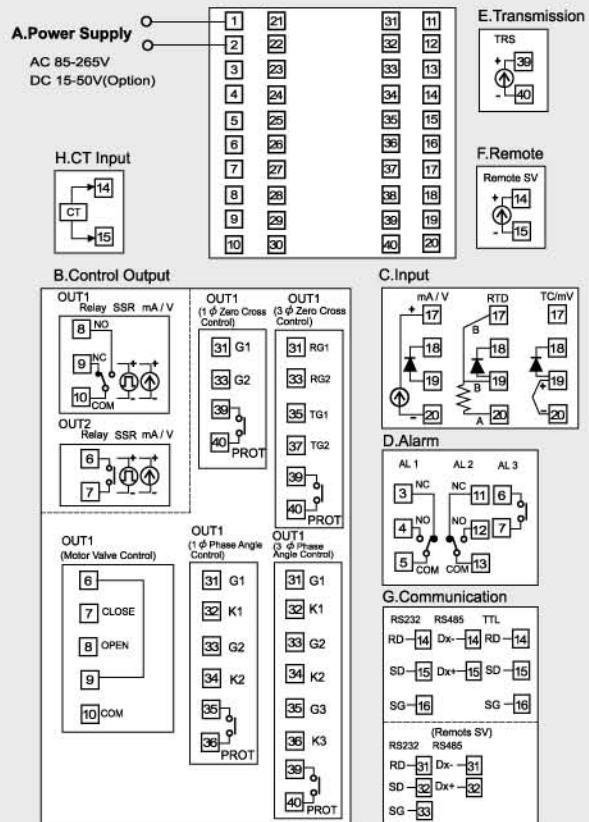
FU72



FU86



FU96



5 Operations

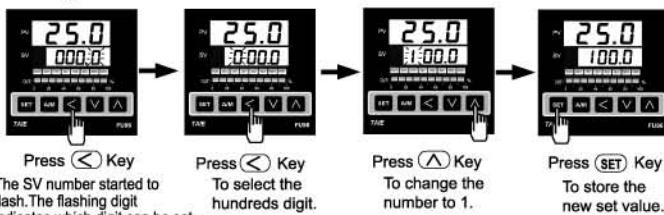
1. Power ON:

Controller will display as following



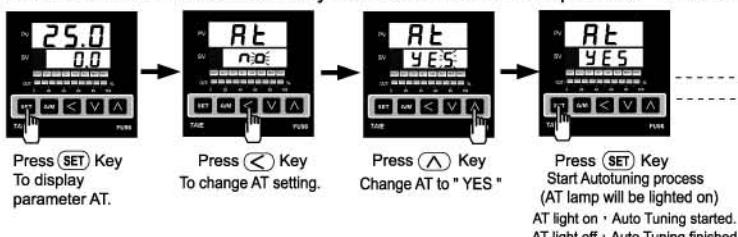
2. Change the Set Value(SV):

Change SV from 0.0 to 100.0



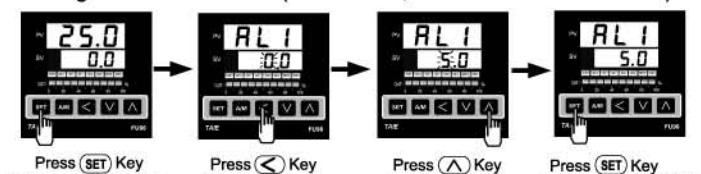
3. Auto Tuning (AT):

Use AT function to automatically calculate and set the optimize PID value for your system.



4. Change the Alarm value:

Change AL1 value to "5.0"(AL1 active ,if PV exceeds SV over 5.0)



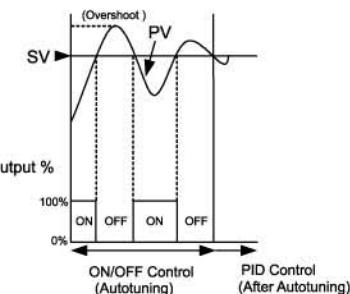
* To change Alarm mode, press **SET** + **<** key 3 seconds to enter Level 3(Input Level) and then change the value of ALD1/ALD2/ALD3.

Autotuning (AT)

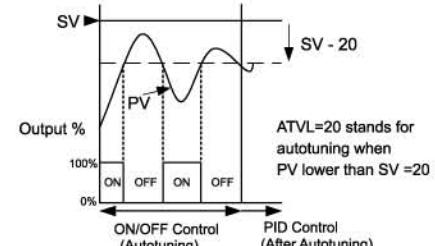
*Set ATVL to prevent overshoot occurred during autotuning process.

To set ATVL,press **SET** key for 3 seconds to enter Level 2 (PID Level) and then change the value.

Factory Default Autotuning
ATVL=0



(Ex.) Autotuning ATVL=20



7 Error Displays

Show status	Explanation	Remedy
in 1E	IN1E : Input 1 Error	Check whether input loop is opened or wiring incorrect.
CJCE	CJCE :Cold Junction Compensation Failed	Check the compensation diode outside controller.
UUU 1	UUU1 : PV is above USPL	Check whether the input value is correct or not.
NNN 1	NNN1 : PV is below LSPL	Check whether the input value is correct or not.
AdCF	ADCF :A/D Convert Failed	Controller needs to be repaired.
RAMF	RAMF :RAM Failed	Controller needs to be repaired.

6 Alarm mode type

▲:SV △: Alarm set value

01	Deviation high alarm with hold action*
	OFF LOW ▲ ON HIGH → PV
11	Deviation high alarm
	OFF LOW ▲ ON HIGH → PV
02	Deviation high alarm with hold action*
	ON LOW ▲ OFF HIGH → PV
12	Deviation low alarm
	ON LOW ▲ OFF HIGH → PV
03	Deviation high/low alarm with hold action*
	ON LOW ▲ OFF ON HIGH → PV
13	Deviation high/low alarm
	ON LOW ▲ OFF ON HIGH → PV

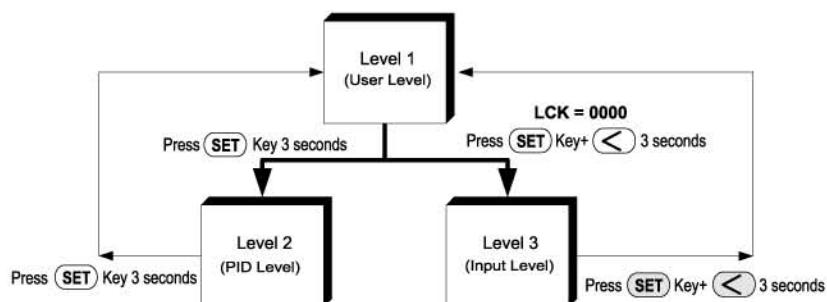
04	Band alarm
	OFF LOW ▲ ON HIGH → PV
05	Process high alarm with hold action*
	OFF ▲ ON HIGH → PV
15	Process high alarm
	OFF ▲ ON HIGH → PV
06	Process low alarm with hold action*
	ON ▲ OFF HIGH → PV
16	Process low alarm
	ON ▲ OFF HIGH → PV

07	Segment End alarm (Only for Programmable controller)
	(1)ALD1~3, set 07
	(2)ALD1~3=Alarm Segment
	(3)ALD1~3 defines as follows: = 0 = flicker alarm = 99.99 = continued alarm = others = alarm ON Delay time
17	Program Run alarm (Only for Programmable controller)
	Run ON Stop OFF AL
08	System failed alarm*(ON)
	Normal OFF Failed ON AL
18	System failed alarm*(OFF)
	Normal ON Failed OFF AL
09	Heater Break Alarm (HBA)
00	No alarm
10	

8 Levels Explanation

Levels Diagram

- When the power is on, it will stay at Level 1(User Level) automatically.
- The controller returns to Level 1 if there is no key operation within 60 seconds.
- In any Level, press **A/M** key twice will return to Level 1.
(FU48 don't have **A/M** key)



Level 1 (User Level)

Process Value Set Value	P1 5.0 ↓ Set
Output Limit	OL-L 1000 ↓ Set
Autotuning	AT YES/no ↓ Set
Alarm 1 set value	AL1 0.0 ↓ Set
Alarm 2 set value	AL2 0.0 ↓ Set
Alarm 3 set value	AL3 0.0 ↓ Set

Return to "P1"

Duel Output display when it has heating or cooling

Level 2 (PID Level)

Proportional band 1 (For output 1)	P1 3.0 ↓ Set
Integral time 1 (For output 1)	I1 240 ↓ Set
Derivative time 1 (For output 1)	D1 60 ↓ Set
Dead-band time	db1 0 ↓ Set
Auto tuning offset value	ATE1L 0 ↓ Set
Output 1 cycle time	CYT1 10 ↓ Set
Hysteresis for output 1 ON/OFF control	HYS1 1 ↓ Set
Proportional band 2 (For output 2)	P2 3.0 ↓ Set
Integral time 2 (For output 2)	I2 240 ↓ Set
Derivative time 2 (For output 2)	D2 60 ↓ Set
Output 2 Cycle time	CYT2 10 ↓ Set
Hysteresis for output 2 ON/OFF control	HYS2 1 ↓ Set
Control gap 1 (For output 1)	GAP1 0 ↓ Set
Control gap 2 (For output 2)	GAP2 0 ↓ Set
Function lock - - -	LCK 0000 ↓ Set

Return to "P1"

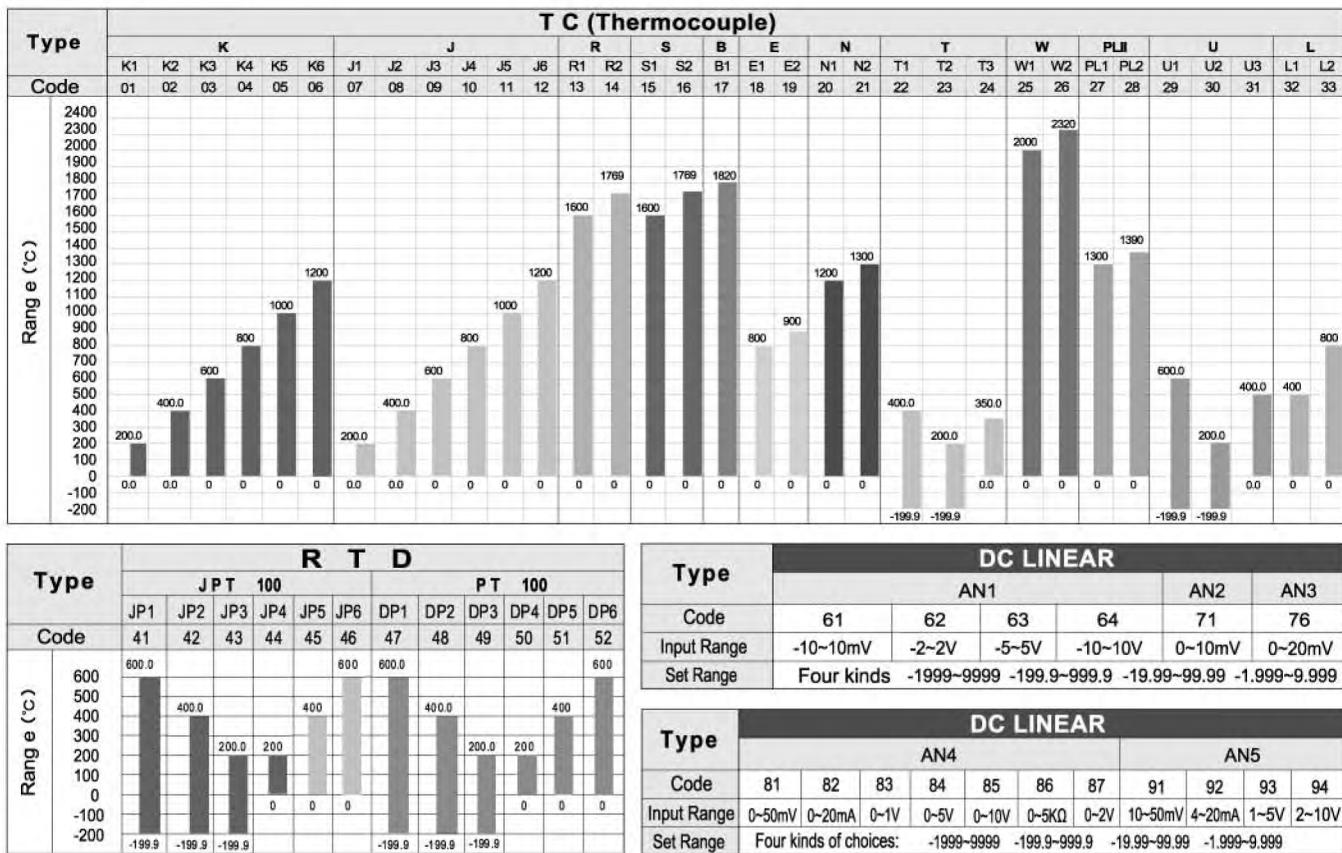
Level 3 (Input Level)

Input type selection	INP1 V2 ↓ Set
Analog input low limit calibration (Used for mA and V input)	ANL1 0 ↓ Set
Analog input high limit calibration (Used for mA and V input)	ANH1 5000 ↓ Set
Decimal point position (Available for mA and V input)	dP 0000 ↓ Set
Lower Set-Point Limit	LSP.L 0.0 ↓ Set
Upper Set-Point Limit	USP.L 4000 ↓ Set
Remote input low limit calibration	RNL1 0 ↓ Set
Remote input high limit calibration	RNH1 5000 ↓ Set
Alarm mode of AL1	RL1 11 ↓ Set
Alarm time of AL1	RLT1 99.59 ↓ Set
Alarm mode of AL2	RL2 0 ↓ Set
Alarm time of AL2	RLT2 99.59 ↓ Set
Alarm mode of AL3	RL3 0 ↓ Set
Alarm time of AL3	RLT3 99.59 ↓ Set
Hysteresis of all Alarm	HYSR 0.0 ↓ Set
Output 1 low limit calibration (Used for mA and V output)	OL1 230 ↓ Set
Output 1 high limit calibration (Used for mA and V output)	OH1 3600 ↓ Set
Output 2 low limit calibration (Used for mA and V output)	OL2 230 ↓ Set
Output 2 high limit calibration (Used for mA and V output)	OH2 3600 ↓ Set
Retransmission low limit calibration	CLO1 0 ↓ Set
Retransmission high limit calibration	CHO1 5000 ↓ Set
Full run time of proportional motor (Used for proportional motor valve control output)	rULC 5 ↓ Set
Used for programmable controller to wait continued operation	CR.E 0.0 ↓ Set
Alarm forward / inverse action setting can force the use of a-contact into b-contact	SEFA 0000 ↓ Set
Communication Protocol Selection	PSL rtU ↓ Set
Communication Bits Configuration	b.E5 a.B1 ↓ Set
ID number	Id 1 ↓ Set
Baudrate	BRD 38400 ↓ Set
SV compensation	S'05 0.0 ↓ Set
PV compensation	P'05 0.0 ↓ Set
Unit of PV & SV	UNIT C ↓ Set
PV Filter	P'FT 200 ↓ Set
Reserved	CRSC 0.0 ↓ Set
Action mode	OLd HEAT ↓ Set
Control algorithm	OPRd P_id ↓ Set
Frequency	H 60Hz ↓ Set

Return to "INP1"

Levels entering available			Parameters can be changed or not
LCK	Level 1 (User Level)	Level 2 (PID Level)	Level 3 (Input Level)
0000	Yes	Yes	Yes
All parameters (Factory set value)			
1111	Yes	Yes	No
All parameters			
0100	Yes	Yes	No
All parameters except Level 3			
0110	Yes	Yes	No
Parameters in Level 1			
0001	Yes	Yes	No
SV" and "LCK"			
0101	Yes	Yes	No
Only "LCK"			

9 Input Types



10 Combination of options and models

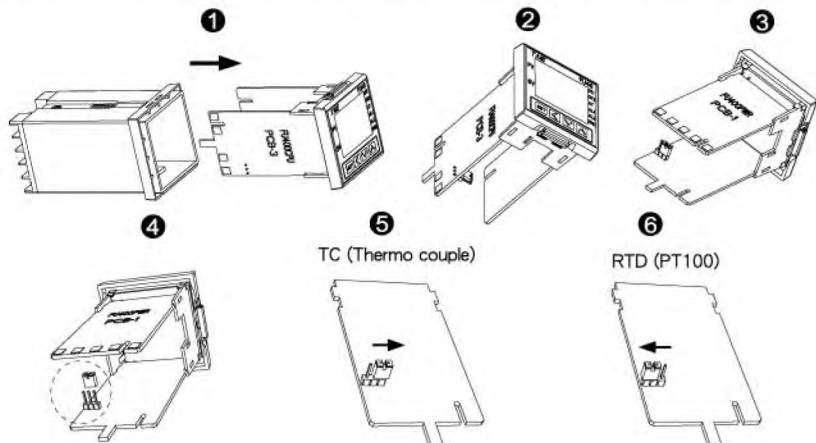
Options Model	RAMP/SOAK PROGRAM	Output 1						Output2	Alarm2	Alarm3	HBA	Transmission	Remote SV	Communication	DC 24V Power
		1φSCR_Z	3φSCR_Z	Motor valve control	1φSCR_P	3φSCR_P									
FU48	○	○	—	○	—	—	○	○	—	○	○	○	○	○	○
FU72	○	○	—	○	○	—	○	○	○	○	○	○	○	○	○
FU86	○	—	—	○	○	—	○	○	○	○	○	○	○	○	○
FU96	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○

○ Available — Not available

* Remote SV function is not available, if HBA Function has been specified.

11 Input Type Change of TC ↔ RTD

1. Take out the main body from outer case: adjust the jumper to the correct place



2. Start power after setting jumper to the correct place

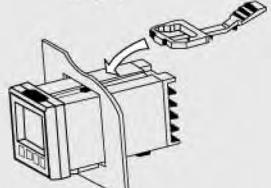
3. Amend the input type from the front membrane to enter in Level 3 to set.

* 4. Please be sure to cut off power and start again after amending input type so that the new parameters could be effective.

5. To change input type of TC or RTD is available but linear input is unavailable. Please ask our local distributor for help.

To mount panel easily

Step 1



Step 2



To push the clamp of special structure design without using screw to the end can be smoothly fixed on the panel.

12 Model & Suffix codes

Model	Output1	Output2	Alarm	TRS	Remote SV	Communication	Input Type	Power	Water/Dust Proof
FU48	—	1	0	1	0	0	0	—	A
(STANDARD)									
FU48	48x48mm	0 None	0 None	0 None	0 None	0 None	0 None	A AC 85~265V	N None
FU72	72x72mm	1 Relay	1 Relay	1 1 Set	1 4~20mA	1 4~20mA	1 TTL	D DC 24V	
FU86	48x96mm	2 Voltage Pulse (SSR Drive)	2 Voltage Pulse (SSR Drive)	2 2 Sets	2 0~20mA	2 0~20mA	2 RS232_MODBUS		W IP65
FU96	96x96mm	3 4~20mA	3 4~20mA	3 3 Sets	A 0~5V	A 0~5V	B RS485_MODBUS		
(RAMP/SOAK Programmable)									
PFU48	48x48mm	A 0~5V	A 0~5V	A HBA*	B 0~10V	C 1~5V			
PFU72	72x72mm	B 0~10V	B 0~10V	B HBA+AL2	D 2~10V	D 2~10V			
PFU86	48x96mm	C 1~5V	C 1~5V	C HBA+AL2+AL3					
PFU96	96x96mm	D 2~10V							
		5 1 φ SCR zero cross control							
		6 3 φ SCR zero cross control							
		7 Motor valve control							
		8 1 φ SCR phase angle control							
		9 3 φ SCR phase angle control							

- : Block means optional functions with additional charge
- Factory set value K2, code 02
- TC Input(K, J.R.S.B.E.N.T.W.PLI.U.L...)setting, can be changed to any types by user
- RTD(JPT 100, PT100)setting, can be changed to any type by user
- TC, RTD, LINEAR can be changed each other but need to change the parts of hardware. For more details, please contact local agents.
- HBA : Heater Break Alarm (HBA must use AL1 as alarm relay)

13 Specifications

Model	FU48	FU72	FU86	FU96
Dimension	48X48mm	72X72mm	48X96mm	96X96mm
Supply voltage	AC 85~265V			
Frequency	50/60 HZ			
Power Consumption	approx 3VA	approx 3VA	approx 4VA	approx 4VA
Memory	Non-volatile memory E2PROM			
Input	Accuracy : 0.2%FS, Sample time : 250ms			
TC	K, J, R, S, B, E, N, T, W5Re/W26Re, PL2, U, L			
RTD	PT100, JPT100			
mA dc	4~20mA, 0~20mA			
Voltage dc	0~1V, 0~5V, 0~10V, 1~5V, 2~10V -10~10mV, 0~10mV, 0~20mV, 0~50mV, 10~50mV			
DP Position	0000, 000.0, 00.00, 0.000 (available for mA or Voltage dc input) According to the input type, °C/°F can be displayed to one decimal			
Output 1	Main control output to HEAT mode or COOL mode			
Relay	SPST type	SPDT type	SPDT type	SPDT type
Voltage Pulse	8A, 240V, electrical life : 100,000 times or more (under the rated load).			
mA dc	For SSR drive. ON:24V, OFF:0V, maximum load current:20mA.			
Voltage dc	DC 4~20mA, 0~20mA. maximum load resistance: 560Ω.			
	DC 0~5V, 0~10V, 1~5V, 2~10V. maximum load current : 20mA.			
Alarm 1	SPST type	SPST type	SPDT type	SPST type
	8A, 240V, electrical life : 100,000 times or more (under the rated load).			
Control algorithms	PID, P, PI, PD, ON/OFF(P=0), FUZZY			
PID range	P : 0~200%, I : 0~3600 Secs, D : 0~900 Secs			
Isolation	Output terminal (control output, alarm, transmission) and Input terminal are isolated separately.			
Isolated resistance	10M Ω or more between input terminals and case(ground) at DC 500V 10M Ω or more between output terminals and case(ground) at DC 500V			
Dielectric strength	1000V AC for 1 minute between input terminals and case(ground) 1500V AC for 1 minute between output terminals and case(ground)			
Operating temperature	0~65°C			
Humidity range	0~50°C / 20~90% RH			
Weight (approx)	approx150g	approx225g	approx225g	approx300g
LED Display(PAT.)	PV:8mm SV:8mm	PV:14mm SV:10mm	PV:8mm SV:8mm	PV:14mm SV:10mm
RAMP/SOAK Program	2 Patterns with 8 segments each. can be linked together as 16 segments use			
Output 2	For heating and cooling control use *Actron mode is opposite with Output 1			
Relay	SPST type	SPST type	SPST type	SPST type
Voltage Pulse	For SSR drive. ON:24V, OFF:0V, maximum load current:20mA.			
mA dc	DC 4~20mA, 0~20mA. maximum load resistance :560Ω.			
Voltage dc	DC 0~5V, 0~10V, 1~5V, 2~10V. maximum load current : 20mA.			
Alarm 2	SPST type	SPDT type	SPDT type	SPDT type
Alarm 3	—	SPST type	SPST type	SPST type
Heater Break Alarm (HBA)	Display Range of Heater Current:0.0~99.9A, Accuracy : 1%FS Included CT :SC-80-T (5.8mm dia, 0.0~80.0A) or SC-100-T(12mm dia, 0.0~99.9A)			
Transmission	Alarm Relay : AL1			
mA dc	Available for PV or SV transmission			
Voltage dc	DC 4~20mA, 0~20mA. maximum load resistance :560Ω.			
Remote SV Input	DC 0~5V, 0~10V, 1~5V, 2~10V. maximum load current : 20mA.			
	4~20mA, 0~20mA, 0~5V, 0~10V, 1~5V, 2~10V are available.			
Communication	Protocol : MODBUS RTU, MODBUS ASCII, TAIE Interface : RS485, RS232, TTL Baudrate : 38400, 19200, 9600, 4800, 2400 bps			
	8 bit, Start bit : 1 bit, Parity : Odd or Even, Stop bit : 1 or 2 bit			
WaterProof/DustProof	IP65			